

# Flyback Controller With Primary Side CC/CV Control

## **General Description**

SY22817A is a single stage Flyback controller targeting at Constant Current/Constant Voltage (CC/CV) applications. Both the output current and voltage are sensed on the primary side, eliminating the opto-isolator and the secondary side feedback circuitry, and minimizing the overall system cost.

SY22817A adopts the quasi-resonant operation and the adaptive PWM/PFM control to achieve the highest average efficiency and the best EMI performance. The no-load switching frequency can be as low as 500Hz, minimizing the no-load power loss.

SY22817A has programmable cable compensation to provide a better load regulation for the output voltage at the cable terminals.

SY22817A provides reliable protections including VIN Over Voltage Protection, Short Circuit Protection (SCP), Over Temperature Protection (OTP), Output voltage OVP/UVP (OVP/UVP), VSEN/ISEN pin short protection, VSEN pin upper divider resistor disconnect protection.

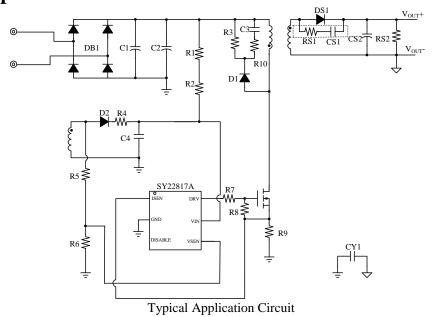
#### **Features**

- Tight PSR CC/CV Regulation Over Entire Operating Range
- QR-mode Operation for High Efficiency
- PWM/PFM Control for High Average Efficiency
- Fast Dynamic Load Transient Response
- Cable Compensation for Better Load Regulation
- Low Start Up Current: 5µA Max
- Minimum Frequency Limitation 500Hz
- Reliable Protections for OVP, UVP, SCP, OTP, OCP
- Reliable Protections for Safety Requirement
- Maximum Switching Frequency Limitation 125kHz
- RoHS Compliant and Halogen Free
- Compact Package: SOT23-6

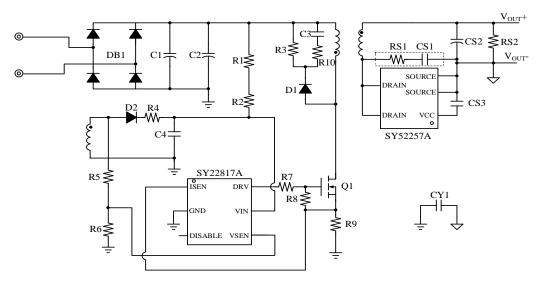
## **Applications**

- AC/DC Adapters
- Battery Chargers

## **Typical Applications**

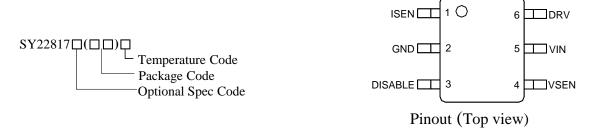






Typical Application Circuit Using SY52257A as the Secondary-Side Synchronous Rectifier

# **Ordering Information**



Ordering Number	Package	Top Mark
SY22817AABC	SOT23-6	2gxyz

x=year code, y=week code, z= lot number code

## **Pinout**

Pin Number	Pin Name	Pin Description
1	ISEN	Current sense pin. Connect this pin to the source of the primary switch.
2	GND	Ground pin.
3	DISABLE	Disable control pin. Pull down to turn off. When this function is not used, it should be floating.
4	VSEN	Output voltage sense pin. This pin receives the auxiliary winding voltage by a resistor divider. The value of the resistor divider also programs the cable impedance. This pin also senses the winding voltage to provide the QR operation.
5	VIN	Power supply pin.
6	DRV	Gate driver pin. Connect this pin to the gate of primary MOSFET.





Absolute Maximum Ratings (Note 1)	
VIN	
DRV	
Supply Current I <sub>VIN</sub>	20mA
VSEN	
ISEN	
DISABLE	
Power Dissipation, @ TA = 25°C SOT23-6	0.6W
Package Thermal Resistance (Note 2)	
SOT23-6, $\theta_{JA}$	170°C/W
SOT23-6, $\theta_{JC}$	130°C/W
Temperature Range	
Lead Temperature (Soldering, 10 sec.)	260°C
Storage Temperature Range	
(*1) Dynamic VSEN Negative Voltage in 50us Duration	
Dynamic VSEN Negative Current in 50us Duration	
Human Body Model ESD, ANSI/ESDA/JEDEC JS-001-2014 (Note 3)	
Latch-up Test Per JEDEC STANDARD NO.78D NOVEMBER 2014 (Note 3)	
Recommended Operating Conditions	
VIN	9V~20V
ISEN	
Junction Temperature Range	40°C to 125°C
Ambient Temperature Range	



## **Electrical Characteristics**

 $(V_{VIN} = 12V \text{ (Note 4)}, T_A = 25^{\circ}\text{C unless otherwise specified)}$ 

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Power Supply Section						
VIN Turn-on Threshold	V <sub>VIN_ON</sub>	V <sub>VIN</sub> increasing	19.5	21.2	22.9	V
VIN Turn-off Threshold	V <sub>VIN_OFF</sub>	V <sub>VIN</sub> decreasing	6.7	7.7	8.7	V
VIN OVP Voltage	V <sub>VIN_OVP</sub>	V <sub>VIN</sub> increasing	22.7	24.0	25.6	V
VIN OVP Voltage Hysteresis	V <sub>VIN_OVP_HYS</sub>	V <sub>VIN_OVP</sub> - V <sub>VIN_ON</sub>	2	3	4.5	V
VIN OVP Blanking time (Note 5)	T <sub>VIN_OVP</sub>		85	128	152	μs
Start Up Current	I <sub>ST</sub>	V <sub>VIN</sub> <v<sub>VIN_OFF</v<sub>	0.5	2	5	μΑ
Operating Current (Note 6)	Ivin	f=100kHz, C <sub>DRV</sub> =800pF	-	3	-	mA
Quiescent Current (Note 6)	$I_Q$	f=500Hz, C <sub>DRV</sub> =800pF	-	170	-	μA
Discharge Current in OVP Mode	Ivin_ovp	V <sub>VIN</sub> =12V	3.9	5.2	6.6	mA
<b>Current Feedback Modulator Section</b>				•		
Internal Reference Voltage	$V_{REF}$		0.41	0.42	0.43	V
ISEN Pin Section						
Current Limit Voltage	V <sub>ISEN_LIM</sub>	V <sub>FBV</sub> <0.4V V <sub>ISEN</sub> increasing	0.7	0.75	0.8	V
Current Limit Voltage	▼ ISEN_LIM	V <sub>FBV</sub> >0.4V V <sub>ISEN</sub> increasing	0.92	0.95	0.98	V
Current Min Voltage	VISEN_MIN		0.22	0.26	0.30	V
Min ON Time	T <sub>ON_MIN</sub>	DRV min width	340	430	520	ns
Voltage Threshold for V <sub>ISEN_LIM</sub> Switch	V <sub>ISEN_SWITCH</sub>	V <sub>ISEN</sub> increasing	310	400	510	mV
Detection Time for VISEN_LIM Switch	Tisen_switch		1.2	1.8	2.4	μs
CC Feedforward Resistor (Note 5)	R <sub>INT</sub>		280	320	360	Ω
Voltage Threshold for ISEN Pin Short	VISEN_SHORT		95	150	205	mV
Time Threshold for ISEN Pin Short (Note 5)	Tisen_short		2.4	3.6	4.8	μs
Enable Time for ISEN Pin Short (Note 5)	Tisen_short_en	Timer start V <sub>VIN_ON</sub>	49	62	78	ms
Peak Current Modulation						
Modulation Minimum Range (Note 5)	VISEN_JITTER_MIN	$V_{ISEN} = V_{ISEN\_MIN}$	4	10	16	mV
Modulation Maximum Range (Note 5)	VISEN_JITTER_MAX	V <sub>ISEN</sub> = V <sub>ISEN_LIM</sub>	48	58	68	mV
Modulation Period (Note 5)	T <sub>JITTER</sub>		200	250	300	μs
VSEN Pin Section						•
OVP Voltage Threshold	V <sub>VSEN_OVP</sub>		1.4	1.5	1.6	V
Number of Consecutive VSEN OVP Enter Hiccup Mode (Note 5)	Nvsen_ovp		-	4	-	
UVP Voltage Threshold (Note 5)	V <sub>VSEN_UVP</sub>		0.75	0.8	0.85	V
Blanking Time for VSEN UVP (Note 5)	Tvsen_uvp		49	62	78	ms
Internal Reference Voltage	V <sub>VSEN_REF</sub>		1.232	1.25	1.268	V
Cable Compensation Coefficient	К3		36	50	64	μΑ/ V
Sourcing Current Threshold for VSEN Pin Short Detection	Ivsen_short		65	100	135	μΑ
Voltage Threshold for VSEN Pin Short Detection (Note 5)	Vvsen_short		30	60	90	mV





Blanking Time for VSEN Pin Short Detection (Note 5)	T <sub>VSEN_SHORT</sub>		85	128	152	μs
Sourcing Current Threshold for Upper Resistor Open	$I_{BO}$		10	18	26	μA
Number of Consecutive Upper Resistor Open Enter Hiccup Mode (Note 5)	N <sub>BO</sub>		-	8	-	
Voltage Threshold for Current Cross Zero (Note 5)	V <sub>VSEN_CCZ</sub>		65	100	135	mV
Voltage Threshold for Zero Zoltage Detection (Note 5)	Vzero		-70	-40	-10	mV
Turn On Delay After Zero Voltage Detection (Note 5)	TDELAY		300	400	500	ns
DISABLE Pin Section	·					
Disable On Threshold	Vdisable_on	V <sub>DISABLE</sub> increasing	0.85	1	1.15	V
Disable Off Threshold	V <sub>DISABLE_OFF</sub>	V <sub>DISABLE</sub> decreasing	0.85	1	1.15	V
Gate Driver Section	<u> </u>	<u> </u>				
Gate Driver Voltage	$V_{ m GATE}$	V <sub>VIN</sub> =V <sub>VIN_OFF</sub> +0.2V	5.9	-	-	V
		V <sub>VIN</sub> =16V	10.2	12	13.8	V
Maximum Source Current (Note 5)	Isource_max		-	160	-	mA
Maximum Sink Current (Note 5)	Isink_max		-	800	-	mA
<b>Protection Timer Section</b>	<u> </u>	<u> </u>				
Max ON Time (Note 5)	Ton_max		19	26	33	μs
Min OFF Time1	Toff_min1	$V_{\rm ISEN} = V_{\rm ISEN\_MIN}$	1.6	1.9	2.3	μs
Min OFF Time2	Toff_min2	$V_{\rm ISEN} = V_{\rm ISEN\_LIM}$	2.1	2.7	3.5	μs
Max OFF Time	T <sub>OFF_MAX</sub>		1.58	2.0	2.42	ms
Max OFF Time for Start Up (Note 5)	Toff_max_st		24.3	36	47.6	μs
Max OFF Time for Load Transient 1 (Note 5)	Toff_max_lt1		90	125	160	μs
Number of Consecutive Max OFF Time for Load Transient 1 (Note 5)	Noff_max_lt1		-	4	-	
Max OFF Time for Load Transient 2 (Note 5)	Toff_max_lt2		190	250	310	μs
Working Time for Load Transient 2 (Note 5)	Toff_max_lt2		6.3	8.0	9.7	ms
Minimum Switching Period	TPERIOD_MIN		6.9	8	9.1	μs
Thermal Section	•			•	•	•
Thermal Shutdown Temperature (Note 5)	T <sub>SD</sub>	Temperature increasing	-	150	-	°C
Thermal Shutdown Temperature Hysteresis (Note 5)	T <sub>SD_HYS</sub>	Temperature decreasing	-	20	-	°C

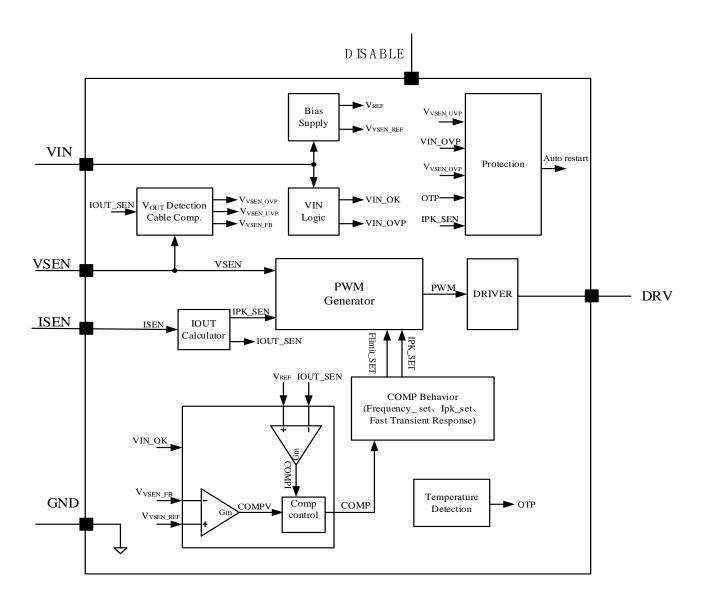
**Note 1**: Stresses beyond the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note 2:  $\theta_{JA}$  is measured in the natural convection at  $T_A = 25$ °C on a low effective single layer thermal conductivity test board of JEDEC 51-3 thermal measurement standard. Test condition: Device mounted on "2 x 2" FR-4 substrate PCB, 2oz copper, with minimum recommended pad on top layer and thermal via to bottom layer ground plane.

- Note 3: Meets JEDEC standards NO.78D november 2014 and JS-001-2014.
- Note 4: Increase VIN pin voltage gradually higher than  $V_{VIN\_ON}$  voltage to start the IC first, then set VIN to 12V.
- Note 5: Guarantee by design.
- Note 6: Application test result.



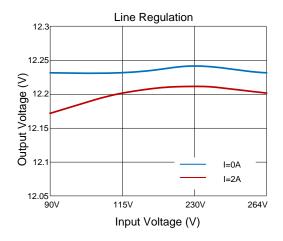
# **Block Diagram**

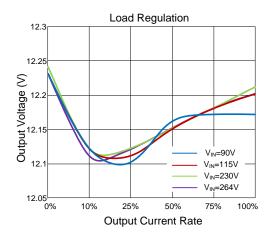


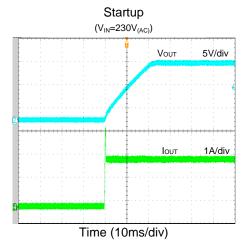


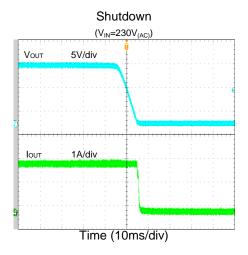
## **Typical Performance Characteristics**

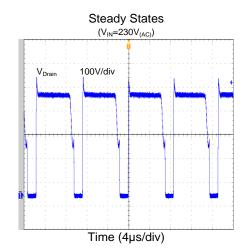
(Test condition: input voltage: 90~264Vac; output spec: 12Vdc\_2A; output cable: 22AWG\_1.2m; Ambient temperature: 25±5 °C; Ambient humidity: 65±25 %.)

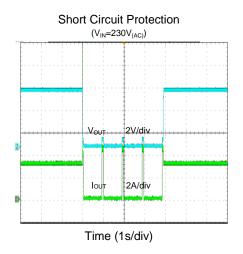




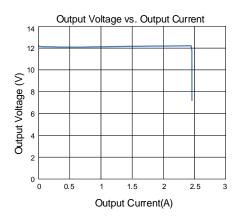


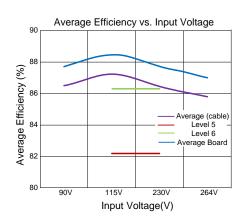




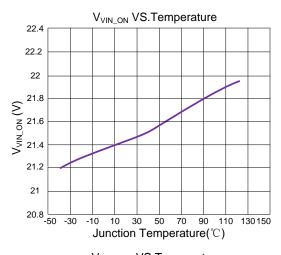


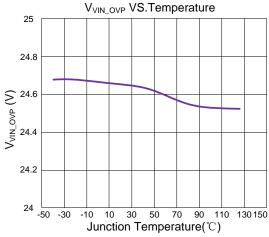


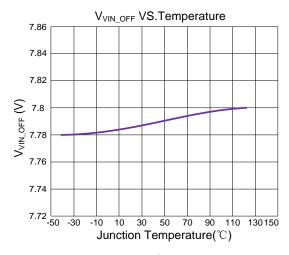


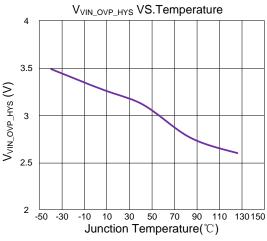


# **Typical Characteristics**

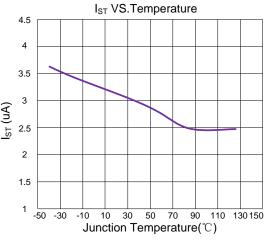


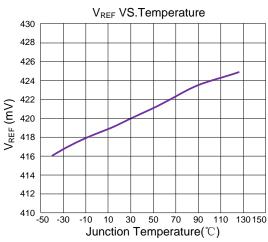


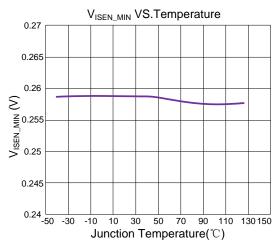


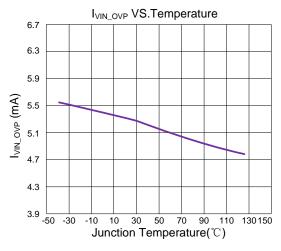


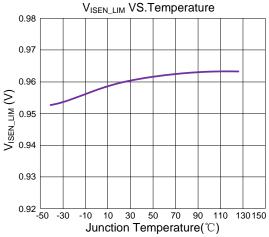


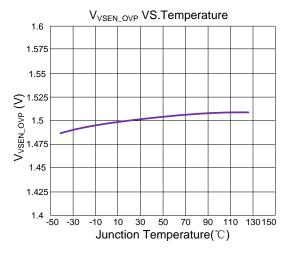




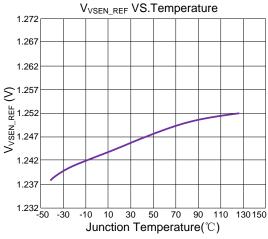


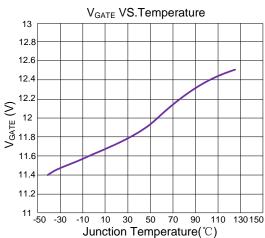


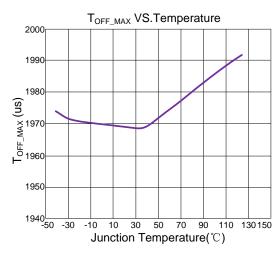


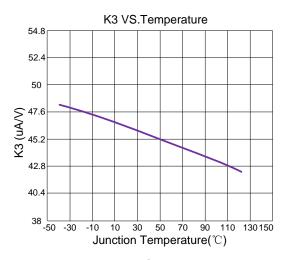


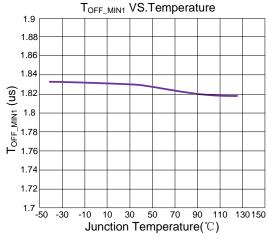


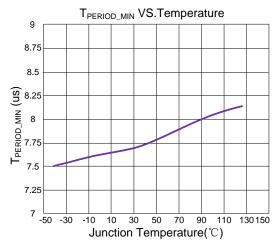












10



## **Operation Principles**

#### **Start-up Operation**

After AC supply is powered on, the rectified BUS voltage ramps up. The capacitor across VIN and GND pins,  $C_{VIN}$ , is charged up by the BUS voltage through a start up resistor  $R_{ST}$ . Once  $V_{VIN}$ , the voltage on the VIN pin, rises up to  $V_{VIN}_{ON}$ , the internal blocks starts the operation.  $V_{VIN}$  will subsequently be pulled down by the power consumption of the circuitry until the auxiliary winding of Flyback transformer can supply sufficient energy to maintain  $V_{VIN}$  above  $V_{VIN}_{OFF}$ .

The start-up procedure is divided into two sections, as shown in Fig.1:  $t_{STC}$  is the  $C_{VIN}$  charged up section, and  $t_{STO}$  is the output voltage built-up section. The start up time  $t_{ST}$  composes of  $t_{STC}$  and  $t_{STO}$ , and usually  $t_{STO}$  is much smaller than  $t_{STC}$ .

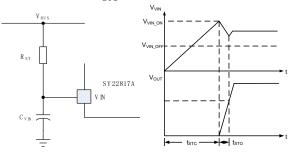


Fig.1 Start up

The start up resistor  $R_{ST}$  and  $C_{VIN}$  are designed by the following rules:

(a) Preset start-up resistor  $R_{ST}$ , make sure that the current through  $R_{ST}$  is larger than  $I_{ST}$  and smaller than  $I_{VIN\_OVP}$ 

$$\frac{V_{\text{BUS\_MAX}}}{I_{\text{VIN OVP}}} < R_{\text{ST}} < \frac{V_{\text{BUS\_MIN}}}{I_{\text{ST}}} (1)$$

Where  $V_{BUS}$  is the BUS line voltage.

**(b)** Select  $C_{VIN}$  to obtain an ideal start-up time  $t_{ST}$ , and ensure the output voltage is built up with only one try.

$$C_{\text{VIN}} = \frac{(\frac{V_{\text{BUS\_MIN}}}{R_{\text{ST}}} - I_{\text{ST}}) \times t_{\text{ST}}}{V_{\text{VIN\_ON}}} (2)$$

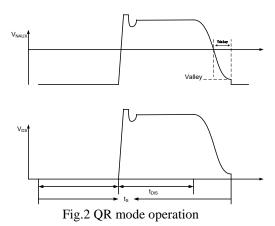
(c) If the  $C_{VIN}$  is not big enough to build up the output voltage with one try, increase  $C_{VIN}$  and decrease  $R_{ST}$ , go back to step (a) and repeat the same design flow until the ideal start up procedure is obtained.

#### **Shut-down Operation**

After AC supply is powered off, the energy stored in the BUS capacitor will be discharged. When the auxiliary winding of Flyback transformer cannot supply enough energy to the VIN pin,  $V_{VIN}$  will decrease. Once  $V_{VIN}$  is below  $V_{VIN\_OFF}$ , the IC will stop working.

#### **Quasi-Resonant Operation (valley detection)**

The Quasi-Resonant switching mode is applied, which means to turn on MOSFET at voltage valley. QR mode operation provides the low turn-on switching losses for Flyback converter.



The voltage across drains and source of the primary MOSFET is reflected to the auxiliary winding of the Flyback transformer. VSEN pin detects the voltage across the auxiliary winding by a resistor divider. As shown in Fig.2, when the voltage on VSEN pin across zero, the MOSFET would be turned on after 400ns delay.

#### Output voltage control (CV control)

In order to achieve primary side constant voltage control, the output voltage is sensed by the auxiliary winding.

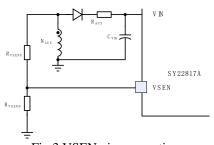


Fig.3 VSEN pin connection

As shown in Fig.4, during OFF time, the voltage across the auxiliary winding is

11

$$V_{\text{AUX}} = (V_{\text{OUT}} + V_{\text{D_F}}) \times \frac{N_{\text{AUX}}}{N_{\text{S}}}$$
 (3)



 $N_{AUX}$  is the turns of auxiliary winding;  $N_S$  is the turns of secondary winding;  $V_{D\_F}$  is the forward voltage of the power diode.

At the current zero-crossing point,  $V_{D\_F}$  is zero, so  $V_{OUT}$  is proportional to  $V_{AUX}$ . The voltage of this point is sampled by the IC as the feedback of output voltage. The resistor divider is designed by

$$\frac{V_{_{VSEN\_REF}}}{V_{_{OUT}}} = \frac{R_{_{_{VSEND}}}}{R_{_{_{VSENU}}} + R_{_{_{VSEND}}}} \times \frac{N_{_{AUX}}}{N_{_{S}}} \quad (4)$$

where  $R_{VSEND}$  and  $R_{VSENU}$  are the low side and high resistors at the VSEN pin, respectively, and  $V_{VSEN\_REF}$  is the internal voltage reference at 1.25V

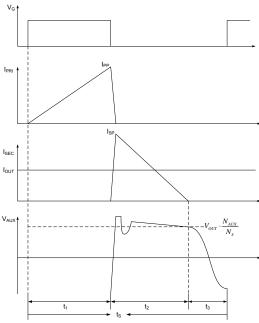


Fig.4 Auxiliary winding voltage waveforms

#### **Output current control (CC control)**

The output current is regulated by SY22817A with primary side detection technology, the maximum output current  $I_{OUT\_LIM}$  can be set by

$$I_{OUT\_LIM} = \frac{k_1 \times V_{REF} \times N_{PS}}{R_S}$$
 (5)

Where  $k_1$  is the output current weight coefficient;  $V_{\text{REF}}$  is the internal reference voltage;  $R_S$  is the current sense resistor.

 $k_1$  and  $V_{REF}$  are all internal constant parameters,  $I_{OUT\_LIM}$  can be programmed by  $N_{PS}$  and  $R_S$ .

$$R_{s} = \frac{k_{1} \times V_{REF} \times N_{PS}}{I_{OUT LIM}}$$
 (6)

 $K_1$  is set to 0.5

When the over current operation or short circuit operation takes place, the output current will be limited at  $I_{\text{OUT\_LIM}}$ . The V-I curve is shown as Fig.5.

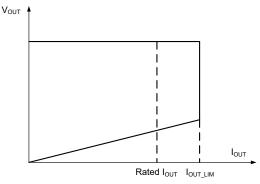


Fig.5 V-I curve

The IC provides line regulation modification function to improve line regulation performance of the output current limit.

#### Cable impedance compensation

SY22817A incorporates the cable impedance compensation to provide a better load regulation of output voltage at cable terminals. When the converter output load increases from no load to full load, the resulting voltage decrease on the output cables are compensated by decreasing the voltage feedback signals, which is shown by Fig. 6.

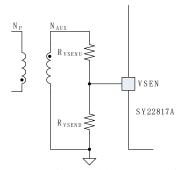


Fig. 6 Cable compensation

$$R_{vsenu} = \frac{R_{cable}}{2k_3 \cdot R_s} \cdot \frac{N_p}{N_s} \cdot \frac{N_{aux}}{N_s} (7)$$

where  $k_3$  is set to 50uA/V,  $R_S$  is the current sense resistor connecting to the ISEN pin.

12



 $R_{cable}$  is the resistance on the cable. The cable compensation effect can be adjusted by change the resistance of  $R_{VSENU}$  to achieve good load regulation of different output cables. The larger  $R_{VSENU}$ , the stronger cable compensation effect will be.

If the output current is below 10% the OCP point, the cable compensation is disabled.

#### **Fault Protection modes**

#### Over-temperature Protection (OTP)

SY22817A includes over-temperature protection (OTP) circuitry to prevent the overheating due to the excessive power dissipation. It will shut down the switching operation when the IC temperature exceeds the OTP threshold, about 150°C. In OTP mode, if the IC temperature decreases by approximately 20°C, the IC will resume the normal operation. For a continuous normal operation, provide an adequate cooling so that the IC temperature does not exceed the OTP threshold.

#### **Short Circuit Protection (SCP)**

When the output is shorted to ground, the output voltage is clamped to zero. The valley signal of the auxiliary winding voltage might not be detected by the VSEN pin. In this case, MOSFET cannot be turned on until maximum off time is reached. IC will shut down until VIN is below  $V_{\rm VIN\_OFF}$ , and then enter the hiccup mode.

When the output voltage is not low enough to disable the valley detection in short condition, SY22817A will operate in CC mode until VIN decreases below  $V_{\text{VIN\_OFF}}$ . As shown in Fig.7, a filter resistor  $R_{\text{AUX}}$  is needed to prevent the SCP function from being affected by the voltage spikes of the auxiliary winding,

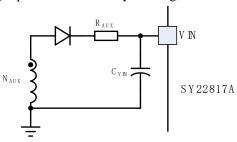


Fig. 7 Filter resistor R<sub>AUX</sub>

#### VIN voltage OVP

When the VIN voltage exceeds  $V_{VIN\_OVP}$  threshold, SY22817A will stop switching and discharge the VIN voltage. Once  $V_{VIN}$  is below  $V_{VIN\_OFF}$ , the SY22817A will shut down and VIN will be charged again.

#### **Output voltage OVP**

When the VSEN pin signal exceeds V<sub>VSEN\_OVP</sub> threshold, reflecting an output over-voltage condition, SY22817A

will stop switching and discharge the VIN voltage. Once  $V_{VIN}$  is below  $V_{VIN\_OFF}$ , the IC will shut down and then enter the hiccup mode.

#### Output voltage UVP

When the VSEN pin signal less than  $V_{VSEN\_UVP}$ , reflecting an output under-voltage condition, SY22817A will stop switching and discharge the VIN voltage. Once  $V_{VIN}$  is below  $V_{VIN\_OFF}$ , the IC will shut down and then enter the hiccup mode.

#### **VSEN** pin short protection

The SY22817A has a protection against the faults caused by shorting VSEN pin to GND. When the VSEN voltage does not reach the sense protection trigger level at the end of startup, the VSEN pin is deemed shorting to GND, and the protection is activated: the IC stops switching and discharge the VIN voltage. Once  $V_{\rm VIN}$  decreases below  $V_{\rm VIN\_OFF}$ , the IC will shut down and then enter the hiccup mode. In order to ensure reliable detection, the pull-down resistor at VSEN pin should be larger than  $2k\Omega$ .

#### **ISEN** pin short protection

The SY22817A has a protection against the faults caused by shorting ISEN pin to GND. If ISEN short is detected at startup the IC stops switching and discharge the VIN voltage. Once  $V_{\text{VIN}}$  decreases below  $V_{\text{VIN\_OFF}}$ , the IC will shut down and then enter the hiccup mode.

# <u>VSEN pin upper divider resistor disconnect</u> protection

If the upper divider resistor disconnected lasting for 8 switching cycles, the IC will stop switching and discharge the VIN voltage. Meanwhile, limit the  $V_{\rm ISEN}$  at  $V_{\rm I\_MIN}$ . Once  $V_{\rm VIN}$  is below  $V_{\rm VIN\_OFF}$ , the SY22817A will shut down and VIN will be charged again.

# **Power Supply Design Considerations**

#### Transformer Design Considerations (NPS and LM)

 $N_{\text{PS}}$  is limited by the electrical stress of the power MOSFET:

$$N_{PS} \le \frac{V_{MOS\_(BR)DS} \times 90\% - \sqrt{2}V_{AC\_MAX} - \Delta V_{S}}{V_{OUT} + V_{D} F}$$
(8)

where  $V_{MOS\_(BR)DS}$  is the breakdown voltage of MOSFET.  $V_{D\_F}$  is the forward voltage of secondary power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber during OFF time.

In Quasi-Resonant mode, each switching period cycle,  $t_S$ , consists of three parts: current rising time  $t_1$ , current falling time  $t_2$  and quasi-resonant time  $t_3$  shown in Fig.8.

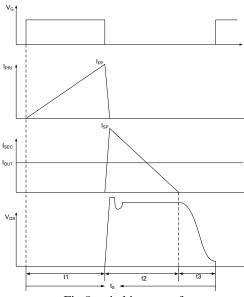


Fig.8 switching waveforms

Under the conditions of the minimum input AC RMS voltage and full load, the switching frequency is minimum while the peak current through MOSFET is maximum.

Once the minimum frequency  $f_{S\_MIN}$  is set, the inductance of the transformer could be designed. The design flow is shown below:

(a)Select N<sub>PS</sub>

$$N_{PS} \le \frac{V_{MOS\_(BR)DS} \times 90\% - \sqrt{2}V_{AC\_MAX} - \Delta V_s}{V_{OUT} + V_{D.F}}$$
 (9)

- (b) Preset minimum frequency f<sub>S\_MIN</sub>
- (c) Compute inductor  $L_M$  and maximum primary peak current  $I_{P\_PK\_MAX}$

$$\begin{split} I_{P\_PK\_MAX} &= \frac{2P_{OUT}}{\eta \times V_{DC\_MIN}} + \frac{2P_{OUT}}{\eta \times N_{PS} \times (V_{OUT} + V_{D\_F})} \\ &+ \pi \sqrt{\frac{2P_{OUT}}{\eta} \times C_{Drain} \times f_{S\_MIN}} \end{split} \tag{10}$$

$$L_{\rm M} = \frac{2P_{\rm OUT}}{\eta \times I_{\rm P\_PK\_MAX}^2 \times f_{\rm S\_MIN}} (11)$$

where  $C_{Drain}$  is the parasitic capacitance at drain of MOSFET,  $\eta$  is the efficiency, and  $P_{OUT}$  is the rated full load power

(d) Compute current rising time  $t_1$  and current falling time  $t_2$ 

$$t_1 = \frac{L_M \times I_{P\_PK\_MAX}}{V_{BUS}} (12)$$

$$t_{2} = \frac{L_{M} \times I_{P_{-}PK_{-}MAX}}{N_{PS} \times (V_{OUT} + V_{D_{-}F})} (13)$$

$$t_{s} = \frac{1}{f_{s \text{ MIN}}} (14)$$

(e) Compute primary maximum RMS current I<sub>P\_RMS\_MAX</sub> for the transformer fabrication.

$$I_{P_{-RMS_{-}MAX}} = \frac{\sqrt{3}}{3} I_{P_{-PK_{-}MAX}} \times \sqrt{\frac{t_{1}}{t_{s}}}$$
 (15)

(f) Compute secondary maximum peak current  $I_{S\_PK\_MAX}$  and RMS current  $I_{S\_RMS\_MAX}$  for the transformer fabrication.

$$I_{S\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} (16)$$

$$I_{S_{-RMS_{-}MAX}} = \frac{\sqrt{3}}{3} N_{PS} \times I_{P_{-}PK_{-}MAX} \times \sqrt{\frac{t_2}{t_S}}$$
 (17)

#### **Transformer Design Considerations**

The key transformer parameters are shown below:

Necessary parameters	
Primary to Secondary Turns ratio	N <sub>PS</sub>
Inductance	L <sub>M</sub>
Primary maximum current	I <sub>P_PK_MAX</sub>
Primary maximum RMS current	I <sub>P_RMS_MAX</sub>
Secondary maximum RMS current	I <sub>S_RMS_MAX</sub>

The design rules are as followed:

- (a) Select the magnetic core style, identify the effective area  $A_{\text{e}}$ .
- (b) Preset the maximum magnetic flux  $\Delta B$

 $\Delta B=0.22\sim0.28T$ 



(c) Compute primary turn N<sub>P</sub>

$$N_{P} = \frac{L_{M} \times I_{P\_PK\_MAX}}{\Delta B \times A_{a}} (18)$$

(d) Compute secondary turn  $N_{\text{S}}$ 

$$N_{\rm S} = \frac{N_{\rm P}}{N_{\rm PS}} (19)$$

(e) Compute auxiliary turn N<sub>AUX</sub>

$$N_{AUX} = N_S \times \frac{V_{VIN}}{V_{OUT}}$$
 (20)

where  $V_{VIN}$  is the working voltage of VIN pin (9V~20V is recommended).

(f) Select an appropriate wire diameter

With I<sub>P\_RMS\_MAX</sub> and I<sub>S\_RMS\_MAX</sub>, select appropriate wire to achieve the current density from 4A/mm<sup>2</sup> to 10A/mm<sup>2</sup>.

(g) If the window area of the core and bobbin is not enough, reselect the core style, go to (a) and redesign the transformer until the ideal transformer is achieved.

#### **Mosfet Selection**

Under the conditions of the maximum input voltage and full load, the voltage stress of primary power MOSFET is maximum;

$$V_{\text{MOS\_DS\_MAX}} = \sqrt{2}V_{\text{AC\_MAX}} + N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D\_F}}) + \Delta V_{\text{S}}$$
 (21)

where  $V_{AC\_MAX}$  is maximum input AC RMS voltage,  $N_{PS}$  is the primary to secondary turns ratio of the Flyback transformer and  $V_{OUT}$  is the rated output voltage.

Under the conditions of the minimum input voltage and full load, the current stress of power MOSFET is maximum.

$$I_{\text{MOS\_PK\_MAX}} = I_{\text{P\_PK\_MAX}} (22)$$

$$I_{MOS\_RMS\_MAX} = I_{P\_RMS\_MAX}$$
 (23)

Where  $I_{P\_PK\_MAX}$  is maximum primary peak current.

#### **Diode Selection**

Under the conditions of the maximum input voltage and full load, the voltage stress of secondary power diode is maximum;

$$V_{D_{LR\_MAX}} = \frac{\sqrt{2}V_{AC\_MAX}}{N_{PS}} + V_{OUT}$$
 (24)

where  $V_{AC\_MAX}$  is maximum input AC RMS voltage,  $N_{PS}$  is the primary to secondary turns ratio of the Flyback transformer and  $V_{OUT}$  is the rated output voltage.

Under the conditions of the minimum input voltage and full load, the current stress of power diode is maximum.

$$I_{D PK MAX} = N_{PS} \times I_{P PK MAX}$$
 (25)

$$I_{DAVG} = I_{OUT} (26)$$

Where I<sub>P\_PK\_MAX</sub> is maximum primary peak current.

#### **Input Capacitor CBUS Selection**

Generally, the input capacitor C<sub>BUS</sub> is selected by

$$C_{RUS} = 2 \sim 3\mu F/W$$
,

or more accurately by

$$C_{BUS} = \frac{\arcsin(1 - \frac{\Delta V_{BUS}}{\sqrt{2}V_{AC\_MIN}}) + \frac{\pi}{2}}{\pi} \times \frac{P_{OUT}}{\eta} \times \frac{1}{2f_{IN}V_{AC\_MIN}^{2}[1 - (1 - \frac{\Delta V_{BUS}}{\sqrt{2}V_{AC\_MIN}})^{2}]}$$
(27)

Where  $\Delta V_{BUS}$  is the voltage ripple of BUS line.

#### **RCD** snubber for MOSFET selection

The power loss of the snubber P<sub>RCD</sub> is evaluated as:

$$P_{\text{RCD}} = \frac{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D_F}}) + \Delta V_{\text{S}}}{\Delta V_{\text{S}}} \times \frac{L_{\text{K}}}{L_{\text{M}}} \times P_{\text{OUT}} (28)$$

where  $V_{OUT}$  is the output voltage,  $V_{D_-F}$  is the forward voltage of the power diode,  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber,  $L_K$  is the leakage inductor,  $L_M$  is the inductance of the Flyback transformer and  $P_{OUT}$  is the output power.



The R<sub>RCD</sub> is calculated as:

$$R_{RCD} = \frac{(N_{PS} \times (V_{OUT} + V_{D_{\_F}}) + \Delta V_{S})^{2}}{P_{RCD}}$$
(29)

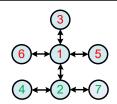
The C<sub>RCD</sub> is calculated as:

$$C_{\text{RCD}} = \frac{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D_F}}) + \Delta V_{\text{S}}}{R_{\text{RCD}} f_{\text{S}} \Delta V_{\text{C RCD}}} (30)$$

## **Layout Considerations**

A proper PCB design must follow the below guidelines: (a) To achieve a good EMI performance and to reduce the line frequency voltage ripples, the output of the bridge rectifier should be connected to the BUS line capacitor first, then to the switching circuit.

- (b) The circuit loop of all switching circuit should be kept as small as possible: primary power loop, secondary loop and auxiliary power loop.
- (c) The connection of primary ground is recommended as:



Ground ①: ground of BUS line capacitor.

Ground ②: ground of bias supply capacitor.

Ground ③: ground node of auxiliary winding.

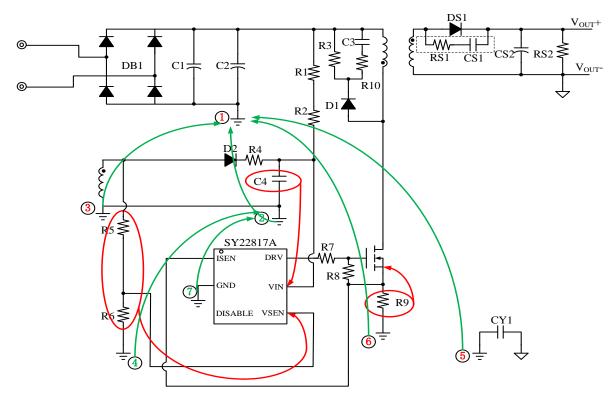
Ground 4: ground node of divider resistor.

Ground ⑤: primary ground node of Y capacitor.

Ground 6: ground node of current sample resistor.

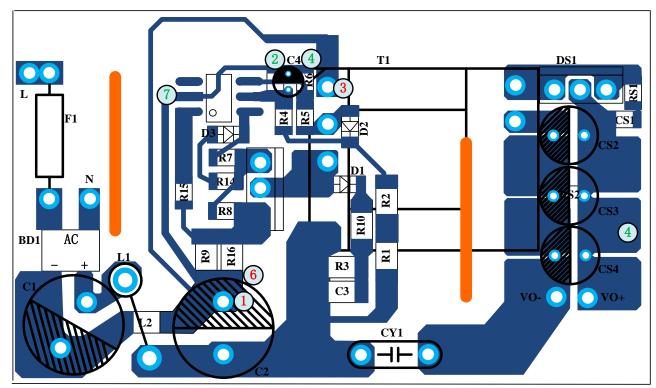
Ground ⑦: ground of IC GND.

- (d) Bias supply trace should be connected to the bias supply capacitor first and then to the GND pin. The bias supply capacitor should be put right beside the IC.
- (e) The loop consisting of 'Source pin current sense resistor GND pin' should be kept as small as possible.
- (f) The resistor divider connected to VSEN pin is recommended to be put close to the IC.



Note: Ground node of current sample resistor must be connected to the ground of bus line capacitor





Example layout

## **Design Notes**

- 1. At no load, the secondary side diode freewheeling time should be more than 2.3μs.
- 2. VIN voltage should be designed to higher than 11V for all conditions.
- 3. RCD snubber's influence:
  - At no load or light load, the off-time of main switch is very long and the snubber capacitor's voltage may be discharged to a small value. When the primary switch turns on and then turns off, the primary winding current needs a longer than normal time to charge up the snubber capacitor. This might affect the feedback voltage sensing. If Imin (Imin=0.26V/Rs) is 0.1A, the snubber capacitor should be no larger than 470pF.
- 4. At heavy load, the peak-to-peak voltage at the Vsen pin should be less than approximately 100mVp-p after off-min time (2.1μs). This can be guaranteed by decreasing the leakage inductance and using proper RCD snubber.
- 5.  $R_{VSENU}$  is the upper resistor of the divider. Normally, its value is recommended between  $10k\Omega\sim65k\Omega$ .
- 6. In order to ensure the CC/CV loop stability, the output capacitor should use the following formula to estimate: Cout= 3.7m\*Iou t/Vout.
  - For example, in the 5V/2A output case, Cout=3.7\*2/5=1.48mF. The output capacitor can choose from 1270uF to 1680uF. On the other hand, switching frequency ripple should also be considered. If the switching frequency ripple is too large, increase the capacitance of Cout properly or use low ESR capacitor.



## **Design Example**

A design example of typical application is shown below step by step. (Cable Test) Note: All selected parameter (set value) need to adjust according to the practical condition.

#### **#1. Identify design specification**

Design Specification				
$V_{AC}(RMS)$	90V~264V	V <sub>OUT</sub>	12V	
$I_{OUT}$	2A	η	90%	

#### #2. Transformer design (NPS, LM, NP, NS, NAUX)

#### (1) Refer to Transformer selection (NPS and LM)

Conditions					
V <sub>AC_MIN</sub>	90V	V <sub>AC_MAX</sub>	264V		
$\Delta V_{S}$	70V	V <sub>MOS_(BR)DS</sub>	600V		
P <sub>OUT</sub> (Max)	24W	$V_{D_{\perp}F}$	1V		
C <sub>Drain</sub>	100pF	f <sub>S_MIN</sub>	55kHz		
$\Delta V_{BUS}$	30% V <sub>BUS_MIN</sub>				

#### (a) Compute turns ratio $N_{\text{PS}}$ first

$$\begin{split} N_{PS} & \leq \frac{V_{MOS\_(BR)DS} \times 90\% \text{-}\sqrt{2}V_{AC\_MAX} \text{-}\Delta V_{S}}{V_{OUT} + V_{D\_F}} \\ & = \frac{600V \times 0.9 \text{-}\sqrt{2} \times 264V \text{-}70V}{12V + 1V} \\ & = 7.434 \end{split}$$

N<sub>PS</sub> is set to

$$N_{PS} = 7.25$$

(b)f<sub>S\_MIN</sub> is preset

$$f_{S,MIN} = 55kHz$$

(c) Compute inductor  $L_{M}$  and maximum primary peak current  $I_{P\_PK\_MAX}$ 

$$\begin{split} I_{P\_{PK\_MAX}} &= \frac{2P_{OUT}}{\eta \times \left(\sqrt{2}V_{AC\_MIN} - \Delta V_{BUS}\right)} + \frac{2P_{OUT}}{\eta \times N_{PS} \times (V_{OUT} + V_{D\_F})} + \pi \sqrt{\frac{2P_{OUT}}{\eta} \times C_{Drain} \times f_{S\_MIN}} \\ &= \frac{2 \times 24W}{0.9 \times (\sqrt{2} \times 90V - 0.3 \times \sqrt{2} \times 90V)} + \frac{2 \times 24W}{0.9 \times 7.25 \times (12V + 1V)} + \pi \times \sqrt{\frac{2 \times 24W}{0.9} \times 100pF \times 55kHz} \\ &= 1.218A \end{split}$$





$$\begin{split} L_{\scriptscriptstyle M} &= \frac{2 P_{\scriptscriptstyle OUT}}{\eta \times I_{\scriptscriptstyle P\_PK\_MAX}^2 \times f_{\scriptscriptstyle S\_MIN}} \\ &= \frac{2 \times 24 W}{0.9 \times (1.218 A)^2 \times 55 \text{kHz}} \\ &= 0.653 \text{mH} \end{split}$$

Set:  $L_M$ =0.65mH. (Note: the actual value generally less than the compute value )

(d) Compute current rising time t<sub>1</sub> and current falling time t<sub>2</sub>

$$t_{_{1}} = \frac{L_{_{M}} \times I_{_{P\_PK\_MAX}}}{V_{_{BUS-MIN}}} = \frac{0.65 mH \times 1.218 A}{\sqrt{2} \times 90 V} = 6.222 \mu s$$

$$t_2 = \frac{L_{\text{M}} \times I_{\text{P\_PK\_MAX}}}{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D\_F}})} = \frac{0.65 \text{mH} \times 1.218 \text{A}}{7.25 \times (12 \text{V} + 1 \text{V})} = 8.402 \mu \text{s}$$

$$t_{_{3}}\!\!=\!\!\pi\!\times\!\!\sqrt{L_{_{M}}\!\times\!C_{_{Drain}}}\!=\!\!\pi\!\times\!\!\sqrt{0.65mH\!\times\!100pF}\!=\!\!0.801\mu s$$

$$t_s = t_1 + t_2 + t_3 = 6.222 \mu s + 8.402 \mu s + 0.801 \mu s = 15.42 \mu s$$

(e) Compute primary maximum RMS current I<sub>P\_RMS\_MAX</sub> for the transformer fabrication.

$$I_{P\_RMS\_MAX} = \frac{\sqrt{3}}{3} I_{P\_PK\_MAX} \times \sqrt{\frac{t_1}{t_s}} = \frac{\sqrt{3}}{3} \times 1.218 A \times \sqrt{\frac{6.222 \mu s}{15.42 \mu s}} = 0.447 A$$

(f) Compute secondary maximum peak current I<sub>S\_PK\_MAX</sub> and RMS current I<sub>S\_RMS\_MAX</sub> for the transformer fabrication.

$$I_{S\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} = 7.25 \times 1.218A = 8.833A$$

$$I_{S\_RMS\_MAX} = N_{PS} \times \frac{\sqrt{3}}{3} I_{P\_PK\_MAX} \times \sqrt{\frac{t_2}{t_s}} = 7.25 \times \frac{\sqrt{3}}{3} \times 1.218 A \times \sqrt{\frac{8.402 \mu s}{15.42 \mu s}} = 3.764 A$$

#### (2) Refer to Transformer number of turns selection (NP, NS, NAUX)

- (a) Select the magnetic core style, identify the effective area  $A_e$ . There select EE22 thickened for compute example. Its  $A_e$  is 48.7 mm<sup>2</sup>. The EE22 thickened can be replaced by other reasonable magnetic core style.
- (b) Preset the maximum magnetic flux  $\Delta B.$  Usually  $\Delta B{=}0.22{\sim}0.28T$  .

Set:  $\Delta B=0.28T$ .

(c) Compute primary turn N<sub>P</sub>

$$N_{P} = \frac{L_{M} \times I_{P\_PK\_MAX}}{\Delta B \times A_{e}} = \frac{0.65 * 10^{-3} * 1.218A}{0.28 * 48.7 * 10^{-6}} = 58.073$$

Set:  $N_P = 58$ 





(d) Compute secondary turn N<sub>S</sub>

$$N_{\rm S} = \frac{N_{\rm P}}{N_{\rm PS}} = \frac{58}{7.25} = 8$$

Set:  $N_S=8$ 

(e) Compute auxiliary turn N<sub>AUX</sub>

$$N_{AUX} = N_S \times \frac{V_{VIN}}{V_{OUT}} = 8 * \frac{15}{12} = 10$$

Set: N<sub>AUX</sub>=10

Where  $V_{\text{VIN}}$  is the working voltage of VIN pin (9V~20V is recommended).

(f) Select an appropriate wire diameter

With  $I_{P\_RMS\_MAX}$  and  $I_{S\_RMS\_MAX}$ , select appropriate wire to make sure the current density ranges from  $4A/mm^2$  to  $10A/mm^2$ .

Primary wire diameter selection: current density j is set to 9 A/mm<sup>2</sup>.

The compute primary wire cross-sectional area  $S1 = \frac{I_{P\_RMS\_MAX}}{i} = \frac{0.447}{9} = 0.05 \text{mm}^2$ 

The compute primary wire diameter D1=2\* $\sqrt{\frac{S1}{\pi}}$  = 2\* $\sqrt{\frac{0.05}{\pi}}$  = 0.251mm

Set: D1=0.25mm.

Secondary wire diameter selection: current density j is set to 7 A/mm<sup>2</sup>.

The compute secondary wire cross-sectional area  $S2 = \frac{I_{S\_RMS\_MAX}}{j} = \frac{3.764}{7} = 0.538 \text{mm}^2$ 

The compute secondary wire diameter D2\_1=2\* $\sqrt{\frac{S2/2}{\pi}}$  = 2\* $\sqrt{\frac{0.339/2}{\pi}}$  = 0.585mm

Set: D2=D2\_1\*2=0.6mm\*2.

Consider transformer style, the actual primary and secondary wire diameter can be adjusted for best production.

(g) If the winding area of the core and bobbin is not enough, reselect the core style, go to (a) and redesign the transformer until the ideal transformer is achieved.



(h) Other usually transformer inductance

	Specification	Remark				
Thickened EE22 (90~264Vac,12V2A)						
Primary-Side Inductance	$0.65$ mH $\pm 5\%$	40kHz,1V,25±5 ℃,Hum:65±25%				
Primary-Side Leakage Inductance	50μΗ Maximum	Short One of Secondary Winding				
$N_{P}$	58					
$N_{S}$	8					
$N_{A}$	10					
	RM8 (90~264Vac,5V4A)					
Primary-Side Inductance	$0.97$ mH $\pm 5\%$	40kHz,1V,25±5 °C,Hum:65±25%				
Primary-Side Leakage Inductance	50µH Maximum Short One of Secondary Windi					
$N_P$	64					
$N_{S}$	4					
$N_A$	10					

#### #3\_1. Select primary power mos

#### Refer to Mosfet selection

Known conditions at this step					
V <sub>AC_MAX</sub>	264V	N <sub>PS</sub>	7.25		
V <sub>OUT</sub>	12V	$V_{D_{-}F}$	1V		
$\Delta V_{S}$	70V				

Compute the voltage and the current stress of primary power mosfet

$$V_{MOS\_DS\_MAX} = \sqrt{2}V_{AC\_MAX} + N_{PS} \times (V_{OUT} + V_{D\_F}) + \Delta V_{S} = \sqrt{2} \times 264V + 7.25 \times (12V + 1V) + 70V = 537.6V$$

$$I_{MOS\_PK\_MAX} = I_{P\_K\_MAX} = 1.218A$$

$$I_{MOS\ RMS\ MAX} = I_{P\ RMS\ MAX} = 0.447A$$

#### #3\_2. Select secondary power diode

#### Refer to **Diode selection**

Compute the voltage and the current stress of secondary power diode

$$V_{D_{\_R\_MAX}} = \frac{\sqrt{2}V_{AC\_MAX}}{N_{PS}} + V_{OUT} = \frac{\sqrt{2} \times 264V}{7.25} + 12V = 63.5V$$

$$I_{_{D\_PK\_MAX}}\!=\!\!N_{_{PS}}\!\times\!I_{_{P\_PK\_MAX}}\!=\!\!7.25\!\times\!1.218A\!\!=\!\!8.833A$$

$$I_{\scriptscriptstyle D\_AVG}\!=\!\!2A$$

#### **#4. Select the input capacitor CIN**



Refer to Input capacitor C<sub>BUS</sub>

Known conditions at this	step		
$V_{AC\_MIN}$	90V	$\Delta V_{ m BUS}$	$30\% V_{BUS\_MIN}$

$$C_{\text{BUS}} = \frac{\arcsin(1 - \frac{\Delta V_{\text{BUS}}}{\sqrt{2} V_{\text{AC\_MIN}}}) + \frac{\pi}{2}}{\pi} \times \frac{P_{\text{OUT}}}{\eta} \times \frac{1}{2 f_{\text{IN}} V_{\text{AC\_MIN}}^2 [1 - (1 - \frac{\Delta V_{\text{BUS}}}{\sqrt{2} V_{\text{AC\_MIN}}})^2]}$$

$$= \frac{\arcsin(1 - \frac{0.3 \times \sqrt{2} \times 90V}{\sqrt{2} \times 90V}) + \frac{\pi}{2}}{\pi} \times \frac{24W}{0.9} \times \frac{1}{2 \times 50 \text{Hz} \times 90V^2 \times [1 - (1 - \frac{0.3 \times \sqrt{2} \times 90V}{\sqrt{2} \times 90V})^2]}$$

$$= 48.2 \text{uF}$$

 $=48.2 \mu F$ 

Set: C<sub>BUS</sub>=55 µF

Where  $\Delta V_{BUS}$  is the voltage ripple of BUS line.

#### **#5. Set VIN pin**

#### Refer to Start up

Conditions					
V <sub>BUS_MIN</sub>	$90V \times \sqrt{2}$	V <sub>BUS_MAX</sub>	$264V \times \sqrt{2}$		
I <sub>ST</sub>	5μA (max)	V <sub>VIN_ON</sub>	21.2V (typical)		
I <sub>VIN_OVP</sub>	5.2mA (typical)	$t_{ST}$	3s (designed by user)		

(a) R<sub>ST</sub> is preset

$$R_{_{ST}}\!<\!\frac{V_{_{BUS\_MIN}}}{I_{_{ST}}}\!=\!\frac{90V\!\times\!\sqrt{2}}{5\mu A}\!=\!25.452M\Omega\;\text{,}$$

$$R_{ST} > \frac{V_{BUS\_MAX}}{I_{VIN\_OVP}} = \frac{264V \times \sqrt{2}}{5.2mA} = 71.78k\Omega$$

Set R<sub>ST</sub>

$$R_{ST} = 6M$$

(b) Design C<sub>VIN</sub>

$$C_{\text{VIN}} = \frac{(\frac{V_{\text{BUS\_MIN}}}{R_{\text{ST}}} - I_{\text{ST}}) \times t_{\text{ST}}}{V_{\text{VIN\_ON}}} = \frac{(\frac{90V \times \sqrt{2}}{6M\Omega} - 5\mu\text{A}) \times 3\text{s}}{21.2V} = 2.24\mu\text{F}$$

Set C<sub>VIN</sub>



 $C_{VIN} = 2.2 \mu F$ 

### #6. Set current sense resistor to achieve ideal output current

Refer to Output current control (CC control)

Known conditions at this step			
$\mathbf{k}_1$	0.5	N <sub>PS</sub>	7.25
$V_{REF}$	0.42V	I <sub>OUT_LIM</sub>	2.4A

The current sense resistor is

$$\begin{split} R_{\text{S}} &= \frac{k_{_{1}} \times V_{_{REF}} \times N_{_{PS}}}{I_{_{OUT\_LIM}}} \\ &= \frac{0.5 \times 0.42 V \times 7.25}{2.4 A} \\ &= 0.634 \Omega \end{split}$$

Set R<sub>S</sub>

Rs= $0.6\Omega$ 

#### **#7. Set VSEN pin**

Refer to Output voltage control (CV control)

First compute R<sub>VSENU</sub>

Conditions			
V <sub>OUT</sub>	12V	V <sub>VSEN_REF</sub>	1.25V
R <sub>Cable</sub>	0.130Ω(22AWG 1.2m)	$N_{S}$	8
N <sub>AUX</sub>	10	<b>K</b> <sub>3</sub>	50

$$R_{vsenu} = \frac{N_{_P}}{N_{_S}} \cdot R_{_{Cable}} \cdot \frac{N_{_{AUX}}}{N_{_S}} \cdot \frac{1}{2K_{_3} \cdot R_{_S}} = 19.6 k\Omega$$

Set R<sub>VSENU</sub>

 $R_{VSENU} = 25k\Omega$ 

Then compute  $R_{VSEND}$ 

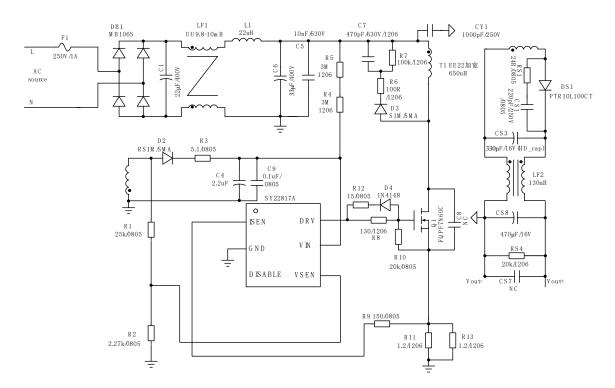
$$R_{\text{VSEND}} = \frac{R_{\text{VSENU}}}{\frac{V_{\text{OUT}}N_{\text{AUX}}}{V_{\text{VSEN\_REF}}N_{\text{S}}}} - 1 = \frac{25k\Omega}{(\frac{12V \times 10}{1.25V \times 8} - 1)} = 2.27k\Omega$$

Set R<sub>VSEND</sub>

 $R_{VSEND}\!=2.27k\Omega$ 

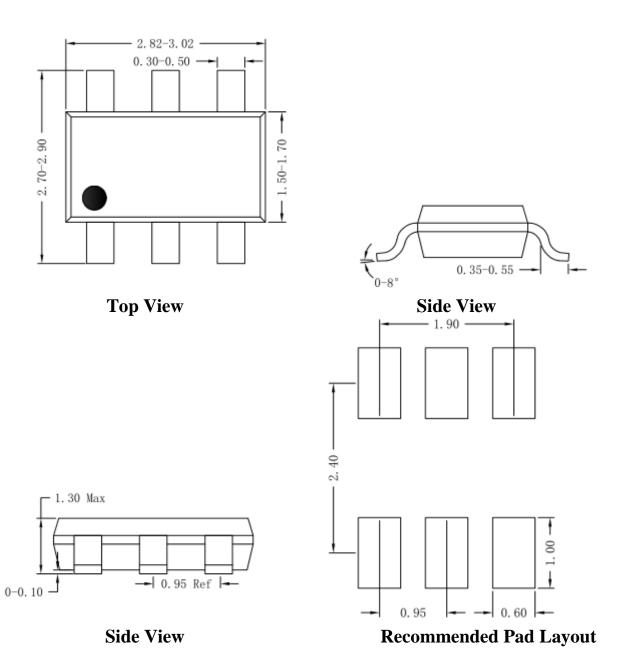


### #8. Final result





# SOT23-6 Package outline & PCB layout design

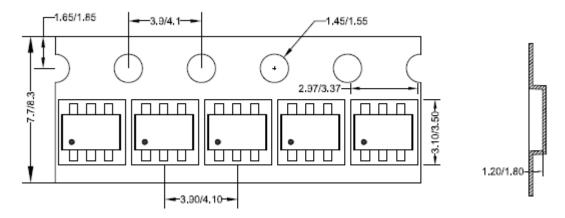


Notes: All dimension in millimeter and exclude mold flash & metal burr.



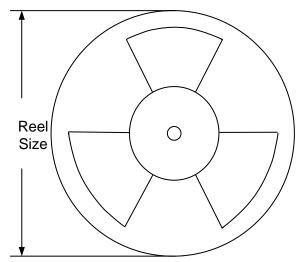
# **Taping & Reel Specification**

## 1. Taping orientation for packages (SOT23-6)



Feeding direction →

## 2. Carrier Tape & Reel specification for packages



Package type	Tape width (mm)	Pocket pitch(mm)	Reel size (Inch)	Trailer length(mm)	Leader length (mm)	Qty per reel
SOT23-6	8	4	7''	280	160	3000



# **Revision History**

The revision history provided is for informational purpose only and is believed to be accurate, however, not warranted. Please make sure that you have the latest revision.

Date	Revision	Change
	Revision 0.9	Initial Release



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